A Unified Multiphase Compositional Flow Simulation Model in PorePy

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The Porous Media Group (PMG)

Key Information

- Dates back to 1985
- Leading international research group in applied and computational mathematics of porous media
- Strong interdisciplinary nature
- Applications: CO₂ storage, geothermal energy, and biomedicine
- Majority of publications within mathematics and geoscience
- Strong interdisciplinary and intersectoral collaboration within CO₂ storage and geothermal energy

Team

- 5 professors (Berre, Dahle, Kumar, Nordbotten, Radu)
- 1 senior researcher 1183 (Keilegavlen)
- 2 researchers (Both, Stefansson)
- 14 PhD students (Jan 2025), 2 postdocs





PorePy

- Open-source code developed at UiB github.com/pmgbergen/porepy
- Mixed-dimensional simulations using domain decomposition of rock, fractures and intersections
- Modeling physical processes using governing equations within subdomains
- Coupling across interfaces between subdomains with dimension gap 1
- Mixed-dimensional domain is a graph, with subdomains as nodes and interfaces as edges
- Meshing on individual subdomains and interfaces resembles that of a standard problem.
- Subdomain models resemble fixed-dimensional problems.
- Coupling manifests as BC or source terms



Schematic representation of rock (dim D), fractures (dim D-1) and intersections (dim D-2).



Higher-dimensional subdomain Ω_h coupled via interface Γ_j to lower-dimensional subdomain Ω_l .



PorePy

- Interface equations and discretizations make the difference from fixed-dimensional problems
- Finite-volume based modeling (MPFA, MPSA, Upwinding)
- Translation of general multiphysics model to numerical format using automatic differentiation adapted to mixed-dimensional setting



Dang et al. Two-level simulation of injection-induced fracture slip and wing-crack propagation in poroelastic media. IJRMMS 160, 105248 (2022).



Stefansson et al. Numerical Modelling of Convection-Driven Cooling, Deformation and Fracturing of Thermo-Poroelastic Media. TiPM 140, 371–394 (2021).



Varela et al. A posteriori error estimates for hierarchical mixed-dimensional elliptic equations. JNM 31 (4), 247-280 (2023).



Motivation

Geothermal System as a Compositional System

Geothermal reservoirs are complex, multiphase systems requiring a unified compositional approach for consistent modeling of fluid behavior.

- Persistent Variables and Equations: Describe system state across all phases
- Flexible EOS: Adaptable to simulate both high-and low-enthalpy geothermal conditions



Schema of conceptual EGS [1].

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[1] Isaka, B.A. et al. (2019). Super-critical CO2 in geothermal systems. SETA, 36, 100547.



Non-Isothermal Compositional Flow Model

Describes the non-isothermal flow and transport of multiple fluid components in a continuum.





Primary Equations (PDEs)



$$\frac{\partial}{\partial t} \left(\phi[\rho h - \rho] + (1 - \phi)\rho_s h_s \right) - \nabla \cdot \left(\sum_{\gamma} f_{\gamma} h_{\gamma} \mathbf{D} \nabla \rho + \mathbf{D}_h \nabla T \right) = q_e$$

Parameters: ϕ : porosity [-] ρ : bulk density [kg/m³] z_{ε} : component overall fraction [-] f_{ε} : fractional flow [-] $\mathbf{D} = \lambda \mathbf{K}$: diffusive tensor $[\mathbf{m}^2/P_{\mathbf{a}\cdot\mathbf{s}}]$ $q_{\mathcal{E}}$: component source/sink term $[kg/m^3s]$ p: pressure [Pa] h: fluid specific enthalpy [J/kg] ρ_s : solid density [kg/m³] \mathbf{D}_h : thermal diffusivity tensor [W/m·K] T: temperature [K] q_e : energy source/sink term [J/m³/s] q : total mass source/ sink term $[kg/m^3s]$

Independent Variables

Assume that $N_p \ge 2$ and $N_c \ge 2$ and phase N_p and component N_c are references. Primary Variables $(N_c + 1)$:

$$\mathbf{x} = [p, h \text{ or } T, z_1, z_2, \dots, z_{N_c-1}].$$

Reference component overall fraction (Closure relation 1):

$$z_{N_c} = 1 - \sum_{\xi=1}^{N_c-1} z_{\xi}$$

Secondary Variables $(N_p(N_c + 1) - 1)$:

$$\begin{aligned} \mathbf{y}_{\mathbf{x}} &= \{ T \text{ or } h \} \cup \{ \mathbf{s}_{\gamma} : \gamma = 1, \dots, N_{p} - 1 \} \cup \{ y_{\gamma} : \gamma = 1, \dots, N_{p} - 1 \} \\ & \cup \{ \chi_{\xi\gamma} : \xi = 1, \dots, N_{c} - 1, \ \gamma = 1, \dots, N_{p} \} \end{aligned}$$

Reference phase quantities (Closure relation 2):



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Model Variables and Well-Posedness





Secondary Equations (Non-PDEs)

Eliminate Secondary (Dangling) Variables



Secondary Equations (Non-PDEs) in PorePy

- Local Equilibrium Equations (Flash Calculations):
 - Solve phase equilibrium problem to determine phase compositions and transitions [2,3]
 - Additional system of non-linear equations (computationally intensive)

• Correlation-Based Calculations:

- Use pre-computed flash results over a discretized space of primary variables
- Rely on correlation formulas to approximate equilibrium properties, e.g., using NaCl-H₂O phase diagram [1]

[1] Driesner, T., & Heinrich, C. A. (2007). The system H2O–NaCl. Part I: Correlation formulae for phase relations in temperature–pressure–composition space from 0 to 1000°C, 0 to 5000 bar, and 0 to 1 XNaCl. Geochimica et Cosmochimica Acta, 71(20), 4880-4901.

[2] Gharbia, I. B., Haddou, M., Tran, Q. H., & Vu, D. T. S. (2021). An analysis of the unified formulation for the equilibrium problem of compositional multiphase mixtures. ESAIM: Mathematical Modelling and Numerical Analysis, 55(6), 2981-3016.
 [3] Lauser, A., Hager, C., Helmig, R., & Wohlmuth, B. (2011). A new approach for phase transitions in miscible multi-phase flow in porous media. Advances in Water Resources, 34(8), 957-966.



Correlation Formulation of NaCl-H₂O System

Evaluation range

For each $\tau \in \mathbf{y}_{\mathbf{x}}$, the correlation [1,2] is given as

$$\begin{split} & ilde{ au} : \mathcal{D} \longrightarrow \mathbb{R} \ & ilde{ extbf{x}} \longmapsto au := ilde{ au}(ilde{ extbf{x}}) \end{split}$$

$$\label{eq:constraint} \begin{split} \mathcal{D} = [0, 5000] \, \text{bar} \times [0, 1000]^\circ \text{C} \times [0, 1] \mbox{ (Use Regula-Falsi} \\ method to transform ~\tilde{\textbf{x}} to \textbf{x}-space). \end{split}$$

Offline

- Compute each τ over the pre-discretized domain of primary quantities with uniform or adaptive resolution
- Derive $\partial_{\mathbf{x}} \tau$ using finite difference method
- Save grid values and derivatives in VTK format

$$\label{eq:x_act} \begin{split} \tilde{\textbf{x}} &= (\textbf{p},\,\textbf{T},\,\textbf{z}_{NaCl}) \\ \textbf{x} &= (\textbf{p},\,\textbf{h},\,\textbf{z}_{NaCl}) \end{split}$$



Saltwater phase diagram [2].

Online

• At any (p,h,z_{NaCl}), use VTK data to interpolate the values and derivatives as needed

 Guo, Z., et al. (2021). swEOS: Salt-water equation of state (1.7.0). Zenodo.
 Driesner, T., & Deinrich, C. A. (2007). Correlation formulae for H₂O-NaCl. Geochimica et Cosmochimica Acta, 71(20), 4880-4901.

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Physical Quantities in Correlation-Based Formulation

• To determine other phase-specific physical quantities, such as density or viscosity, for each phase γ , we define the quantity θ_{γ} by solving the equation:

$$g_{\gamma}(\mathbf{x},\mathbf{y}, heta_{\gamma})=0$$

• Relationship is typically established using suitable equation of state (EoS) combined with appropriate mixture rules



Solution Strategy (Monolithic)

Overall Solution at Each Time Step:

Assume that full system of unknowns is:

$$\mathbf{X}^t = \begin{pmatrix} \mathbf{x}^t \\ \mathbf{y}^t \end{pmatrix}$$

- **Spatial Discretization**: Multipoint Flux Approximation (MPFA) method with an upwind scheme applied for advective terms
- Temporal Discretization: Implicit Euler method

Non-Linear System:

$$\mathbf{G}(\mathbf{X}^t) = \mathbf{0}$$

Newton Linearization:

$$J(\mathbf{X}^{t,n})(\mathbf{X}^{t,n+1}-\mathbf{X}^{t,n})=-G(\mathbf{X}^{t,n})$$



Numerical Experiments

- 1D Advection-Dominated (Constant Temperature):
 - Pure water, single-phase and supercritical fluid flow
 - Pure water, two-phase flow



• 2D Convection-Dominated (Constant Heat Flux) without gravity:



Implementation in PorePy [1]:

Benchmark with CSMP++ (developed by Stephan Matthai and colleagues at ETH Zurich) [2].

[2] Weis, P., Driesner, T., Coumou, D., & Geiger, S. (2014). Hydrothermal, multiphase convection of H2O-NaCl fluids from ambient to magmatic temperatures: A new numerical scheme and benchmarks for code comparison. Geofluids, 14(3), 347-371.



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^[1] Keilegavlen, E., Berge, R., Fumagalli, A., Starnoni, M., Stefansson, I., Varela, J., & Berre, I. (2021). Porepy: An open-source software for simulation of multiphysics processes in fractured porous media. Computational Geosciences, 25, 243-265.

1D Advection-Dominated

Common model parameters:

- Domain: $2000 \times 10m$
- Abs perm: 10^{-15} m² (isotropic)
- Component: H_20
- Relperm: linear
- Pressure and energy equations are active

•
$$\mathbf{x} = (p, h)$$

• Grid cell size: 10m



- At BCs and ICs: $h := \tilde{h}(p, T)$
- $\delta t \in [100, 365]$ days
- Convergence tol: 10^{-3}



1D Advection Dominated (Single-Phase)

Three Cases: Single-Phase/Fluid Flow

Case 1: Liquid Phase

Case 2: Supercritical Fluid

*p*_{in} = 50 MPa,
 *p*_{out} = 25 MPa

• $T_{in} = 350^{\circ}C,$ $T_{out} = 150^{\circ}C$ • $p_{in} = 40 \text{ MPa}$, $p_{out} = 20 \text{ MPa}$

• $T_{in} = 450^{\circ}C$, $T_{out} = 300^{\circ}C$

Case 3: Vapor Phase

- $p_{in} = 15.0 \text{ MPa},$ $p_{out} = 1.0 \text{ MPa}$
- $T_{in} = 500^{\circ}C,$ $T_{out} = 300^{\circ}C$









Case 1: Pure Water Two-Phase (High Pressure Gradient)

- BCs:
 - ▶ $p_{in} = 20.0 \text{MPa}, p_{out} = 1.0 \text{MPa}$
 - ► $T_{in} = 400^{\circ}C, T_{out} = 150^{\circ}C$
- Residual liquid saturation (R_l) : 0.3
- Residual vapour saturation (R_v) : 0.0
- Relperm of liquid:

$$k_{rl}(s_l) = \begin{cases} 0 & \text{if } s_l \leq R_l \\ \frac{s_l - R_l}{1 - (R_l + R_v)} & \text{if } s_l > R_l \end{cases}$$

• Relperm of vapor:

$$k_{rv}(s_v) = \frac{s_v - R_v}{1 - (R_l + R_v)}$$

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Case 1: Pressure -Temperature and Saturation Progressions (High Pressure Gradient)





Case 2: Pure Water Two-phase Flow (Low Pressure Gradient)

- BCs:
 - ▶ $p_{in} = 4.0 \text{MPa}, \ p_{out} = 1.0 \text{MPa}$
 - $\blacktriangleright T_{in} = 300^{\circ}C, \ T_{out} = 150^{\circ}C$
- Residual liquid saturation (R_l) : 0.3
- Residual vapour saturation (R_v) : 0.0
- Relperm of liquid and vapour: same with high pressure gradient case



Case 1: Pressure-Temperature and Saturation Progressions (Low Pressure Gradient)





2D Convection-Dominated with Constant Heat Flux

Pure Water Liquid Phase

- Domain: $9 \times 3 \text{ km}$
- BCs:
 - $p_{top} = 0.1 \text{MPa}, T_{top} = 10^{\circ} \text{C}$
 - Imperbeable sides and bottom
- ICs: $p_{\text{initial}} = \text{hydrostatic pressure}, \ T_{\text{initial}} = 10^{\circ}\text{C}$
- Constant heat flux (q_e) over 1km at bottom center: 5W/m³
- No gravity



[1] Weis, P., Driesner, T., Coumou, D., & Geiger, S. (2014). Hydrothermal, multiphase convection of H2O-NaCl fluids from ambient to magmatic temperatures: A new numerical scheme and benchmarks for code comparison. Geofluids, 14(3), 347-371. UNIVERSITY OF BERGEN

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2D Convection-Dominated with Constant Heat Flux

Temperature-Pressure Evolution after 5 kyrs



Conclusion

- Developed a unified compositional model combined with pre-computed flash calculation for multiphase geothermal reservoir simulation
- Implemented in PorePy for high-enthalpy and single component two-phase flow
- Achieved good agreement with existing benchmark models
- Applications in geothermal energy extraction, predicting temperature-pressure dynamics and phase transitions



Local Equilibrium Model

Motivation:

- Avoid interpolation and additional error.
- Advanced strategies for equilibrium calculations without relying on an a-priori discretized thermodynamic space.
- Step towards generality in terms of thermodynamic modeling (EoS) and parameter space (p, T, h, u, v).

Outline of unified flash

The persistent variable approach requires a *uniform formulation* of the phase equilibrium conditions [1].

- Static phase context γ = 1, 2, ..., N_p.
- Phase appearance & disappearance is handled with inequality constraints $0 \le y_{\gamma} \le 1$.
- Introduction of extended partial fractions $\tilde{\chi}_{\xi\gamma}$ for each phase γ

$$\chi_{\xi\gamma} = \begin{cases} \tilde{\chi}_{\xi\gamma} & y_{\gamma} > 0\\ \frac{\tilde{\chi}_{\xi\gamma}}{\sum_{\zeta} \tilde{\chi}_{\zeta\gamma}} & y_{\gamma} = 0 \end{cases}, \ 0 \le 1 - \sum_{\zeta=1}^{N_{p}} \tilde{\chi}_{\zeta\gamma} ,$$

as mathematical extensions for the case $y_{\gamma} = 0$.

 Ben Gharbia et al. An analysis of the unified formulation for the equilibrium problem of compositional multiphase mixtures. ESAIM (55) 6, 2981-3016 (2021)

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Unified equilibrium conditions: Optimization approach

Locally, we consider the thermodynamic state of the fluid defined in terms of z_ξ and two additional state functions σ

$$\sigma \in \{\{p, T\}, \{p, h\}, \{v, T\}, \{v, u\}, \{v, h\}\}.$$

Secondary Variables $(N_p N_c + 2(N_p - 1) \text{ fractions})$:

$$\begin{split} \tilde{\mathbf{y}}_{\sigma} &= \{ p \text{ and/or } T \} \cup \{ s_{\gamma} : \gamma = 1, \dots, N_p - 1 \} \cup \{ y_{\gamma} : \gamma = 1, \dots, N_p - 1 \} \\ & \cup \{ \tilde{\chi}_{\xi\gamma} : \xi = 1, \dots, N_c, \ \gamma = 1, \dots, N_p \}. \end{split}$$

Reference phase parameters (Closure relation 3):

$$s_{N_p} := 1 - \sum_{\gamma=1}^{N_p-1} s_\gamma, \;\; y_{N_p} := 1 - \sum_{\gamma=1}^{N_p-1} y_\gamma$$

 \rightarrow primary variables can be seen as *transport of thermodynamic target state*, \rightarrow secondary variables as local, non-linear alteration of transport.

Find $\mathbf{y}_{\sigma}^{\star}$ such that

$$\begin{split} \mathbf{y}_{\sigma}^{\star} &= \operatorname*{arg\,min}_{\mathbf{y}} \ f_{\sigma}(\mathbf{y}) \\ \text{with:} \quad z_{\xi} - \sum_{\gamma=1}^{N_{p}} \tilde{\chi}_{\xi\gamma} y_{\gamma} = 0, \ \forall \xi, \\ \quad y_{\gamma} \geq 0, \ \forall \gamma. \end{split}$$

 $f_{\sigma}(\mathbf{y})$ is a function to be minimized depending target state σ . In fact, we again obtain a map

$$\tau_{\sigma}^{\star}: \mathbf{x} \longmapsto \tau_{\sigma}^{\star}(\mathbf{x}) = \mathbf{y}^{\star}$$
,

with τ_{σ}^{*} not being an interpolation, but the solution to the σ -flash problem. Exemplarily,

$$\begin{split} f_{p,T} &= g \quad \text{(Gibbs energy minimization),} \\ f_{p,h} &= -S = \frac{1}{T}(g-h) \quad \text{(entropy maximization).} \end{split}$$

By virtue of thermodynamic relations, the target function can always be chosen to be of the following form [1]:

$$f_{\sigma}(\mathbf{y}) = f_{\sigma}(\mathbf{y}, g(\mathbf{y}))$$



With $f_{\sigma}(\mathbf{y}) = f_{\sigma}(\mathbf{y}, g(\mathbf{y}))$ and standard optimization techniques, the semi-smooth first-order conditions are of form

$$F_{\sigma}(\mathbf{x}, \mathbf{y}) =
abla_{\mathbf{y}} f_{\sigma} = egin{bmatrix} \Lambda(\mathbf{y}) \ \Upsilon_{\sigma}(\mathbf{y}) \ \min\{\Gamma(\mathbf{y}), \lambda(\mathbf{y})\} \end{bmatrix} = 0 \; ,$$

with

$$\Lambda(\mathbf{y}) = \begin{bmatrix} \left(\tilde{\chi}_{\xi\gamma} - \tilde{\chi}_{\xi N_{p}} \frac{\varphi_{\xi N_{p}}}{\varphi_{\xi\gamma}}\right)_{\gamma=1...N_{p}-1} \\ \left(z_{\xi} - \sum_{\gamma=1}^{N_{p}} \tilde{\chi}_{\xi\gamma} y_{\gamma}\right)_{\xi=1...N_{p}} \end{bmatrix}, \ \Gamma(\mathbf{y}) = \begin{bmatrix} (y_{\gamma})_{\gamma=1...N_{p}} \end{bmatrix}, \ \lambda(\mathbf{y}) = \begin{bmatrix} \left(1 - \sum_{\xi=1}^{N_{c}} \tilde{\chi}_{\xi,\gamma}\right)_{\gamma=1...N_{p}} \end{bmatrix}$$

Using the unified formulation and an optimization approach, we arrived at a general mathematical structure of the flash problem, where only Υ_{σ} varies:

$$\Upsilon_{pT} = [-], \quad \Upsilon_{ph} = \left[h - \sum_{\gamma=1}^{N_p} y_{\gamma} h_{\gamma}(\mathbf{y})\right].$$



Coupling with flow & transport

With $G(\mathbf{x}^t, \mathbf{y}^t)$ denoting the discretized balance equations and $\mathbf{x} = [p, h, z_1, \dots, z_{N_c-1}]$, the unified compositional formulation using the isenthalpic flash can be written as

$$egin{bmatrix} G(\mathbf{x}^t,\mathbf{y}^t)\ F_{ph}(\mathbf{x}^t,\mathbf{y}^t) \end{bmatrix} = 0. \end{split}$$

Numerical Solution strategies

While flow & transport progress in some non-zero characteristic time, the local phase equilibrium is instantaneous.

The stiffness of the system in the general case (EoS) makes it difficult to solve above system without a splitting-type approach.



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2D Flash calculations as resolutions of instant-time scale for multiple flow regimes

- A Semi-smooth Newton solver with a Schur complement technique is applied on the global system.
- In between iterations, the flash problem is solved in every cell in parallel.
- The numerical method to obtain τ*(x^t_i) can be any suitable optimization algorithm [1].
- The pT-flash as a subset of the ph-flash can be used in areas with a less volatile flow regime.
- Ongoing work explores above mentioned options.

[1] Vu et al.A new approach for solving nonlinear algebraic systems with complementarity conditions. Application to compositional multiphase equilibrium problems, IMACS (190), 1243-1274 (2021)



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Conclusion

- A persistent variable formulation for both flow & transport problem, and thermodynamic equilibrium problem leads to a global and closed mathematical model.
- Flash calculations can be used to resolve the instantaneous timescale.
- Computational cost, as a price for flexibility, can be significantly compensated for using the unified formulation and an efficient parallelization.

